# MEI MT Problem Set 8<sup>1</sup>

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January 21, 2010

 $<sup>^1 {\</sup>sf Available \ on \ http://personal.lse.ac.uk/carayolt/ec402.htm}$ 

Question

- ►  $y = X\beta + \epsilon$  with X:  $T \times k$  such that X full column rank and  $E(\epsilon|X) = 0$ .
- We consider four different specifications for the variance of the error term:
  - (a)  $E(\epsilon_t^2|X) = \theta_0 + \theta_1 x_{3t}^2 + \frac{\theta_2}{x_{5t}^4}$ , and  $\forall s \neq t, E(\epsilon_s \epsilon_t | X = 0)$ .
  - ► (b)  $E(\epsilon_t^2|X) = \sigma_\nu^2 n_t$ , with  $n_1, ..., n_T$  known, and  $\forall s \neq t, E(\epsilon_s \epsilon_t | X = 0)$ .
  - (c)  $\epsilon_t = \rho \epsilon_{t-1} + \nu_t$ , with  $|\rho| < 1$ ,  $\nu_t$  i.i.d. with (conditional) expected value 0 and finite (conditional) variance  $\sigma_{\nu}^2$ . (The  $\{\epsilon_t\}$  sequence follows an AR(1) process).
  - (d)  $\epsilon_t = \nu_t + \lambda \nu_{t-1}$ , with  $|\rho| < 1$ ,  $\nu_t$  i.i.d. with (conditional) expected value 0 and finite (conditional) variance  $\sigma_{\nu}^2$ . (The  $\{\epsilon_t\}$  sequence follows a *MA*(1) process).
- ► For each specification, we will first write down the variance-covariance matrix of *e*, and second explain how we would implement the FGLS estimator.

- Reminder: GLS = General Least squares; FGLS = Feasible General Least Squares.
- The BLUE estimator under A4Ω is β̂<sub>GLS</sub> = (X'Ω<sup>-1</sup>X)<sup>-1</sup>X'Ω<sup>-1</sup>Y; but Ω is typically unknown so in general GLS has in general only a theoretical appeal.
- It is sometimes possibly to estimate Ω consistently, though (say by Ω(θ̂)), which allows us to use instead β̂<sub>FGLS</sub> = (X'Ω(θ̂)<sup>-1</sup>X)<sup>-1</sup>X'Ω(θ̂)<sup>-1</sup>Y.
- The FGLS estimator has messy finite sample properties. It may be biased and non-linear. However it can be shown that as long as Ω(θ̂) is consistent for Ω, FGLS and GLS are asymptotically equivalent, which implies that it is consistent and asymptotically efficient for β.

- (a)  $E(\epsilon_t^2|X) = \theta_0 + \theta_1 x_{3t}^2 + \frac{\theta_2}{x_{5t}^4}$ , and  $\forall s \neq t, E(\epsilon_s \epsilon_t | X) = 0$ .
- ► Off-diagonal terms will be zeros (no autocorrelation); diagonal terms are given by E(e<sup>2</sup><sub>t</sub>|X) above.

$$\textbf{Hence } V(\epsilon) = c^2 \Omega = \\ \begin{pmatrix} \theta_0 + \theta_1 x_{31}^2 + \frac{\theta_2}{x_{51}^4} & 0 & \cdots & 0 \\ 0 & \theta_0 + \theta_1 x_{32}^2 + \frac{\theta_2}{x_{52}^4} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \theta_0 + \theta_1 x_{3T}^2 + \frac{\theta_2}{x_{5T}^4} \end{pmatrix}$$

- To implement FGLS:
  - The parameters in  $\Omega$  are  $\theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix}$ . If we find a consistent estimator for  $\theta$ , we are done.
  - To obtain this θ: first find β<sub>OLS</sub> from the original equation.
     We know it is not an efficient estimator, but it is consistent.
     Denote the residual as ê.
  - Now: perform the OLS regression of  $\hat{\epsilon_t}^2$  on a constant,  $x_{3t}$  and  $\frac{1}{x_{5t}^4}$ . That the resulting  $\hat{\theta}$  is then consistent for  $\theta$  is true, but not trivial: to be entirely thorough this would need a short proof. I prove it IN THIS CASE in the appendix; for (c) and (d) the proof would be similar in spirit.
  - Define  $\Omega(\hat{\theta})$  as the expression for  $\Omega$  from previous slide, where  $\theta$  is replaced by its consistent estimator  $\hat{\theta}$ .
  - Define  $\hat{\beta}_{FGLS} = (X'\Omega(\hat{\theta})^{-1}X)^{-1}X'\Omega(\hat{\theta})^{-1}Y.$

- ► (b)  $E(\epsilon_t^2|X) = \sigma_{\nu}^2 n_t$ , with  $n_1, ..., n_T$  known, and  $\forall s \neq t, E(\epsilon_s \epsilon_t | X) = 0$ .
- ► Off-diagonal terms will be zeros (no autocorrelation); diagonal terms are given by E(e<sup>2</sup><sub>t</sub>|X) above.

► Hence 
$$V(\epsilon) = \sigma_{\nu}^2 \begin{pmatrix} n_1 & 0 & \cdots & 0 \\ 0 & n_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & n_T \end{pmatrix} = \sigma_{\nu}^2 \Omega.$$

- ► To implement FGLS:
  - The parameters  $n_1, ..., n_T$  are known, so the only unknown parameter here is  $\sigma_{\nu}$ . Since it multiplies every element of the  $\Omega$  matrix, we can apply GLS rather than FGLS here:  $\sigma_{\nu}$  does *not* appear in the GLS formula.

- (c) ε<sub>t</sub> = ρε<sub>t-1</sub> + ν<sub>t</sub>, with |ρ| < 1, ν<sub>t</sub> i.i.d. with (conditional) expected value 0 and finite (conditional) variance σ<sup>2</sup><sub>ν</sub>. (The {ε<sub>t</sub>} sequence follows an AR(1) process).
- This time we will have autocorrelation. In particular, cov(ε<sub>t</sub>, ε<sub>t-1</sub>) = cov(ρε<sub>t-1</sub> + ν<sub>t</sub>, ε<sub>t-1</sub>) = ρσ<sub>ε</sub><sup>2</sup>. Likewise, ∀s, t, cov(ε<sub>t</sub>, ε<sub>s</sub>) = ρ<sup>|t-s|</sup>σ<sub>ε</sub><sup>2</sup>. We could compute σ<sub>ε</sub><sup>2</sup> too: but the nice thing here is that we do not need it.

► Hence 
$$V(\epsilon) = c^2 \Omega = \sigma_{\epsilon}^2 \begin{pmatrix} 1 & \rho & \cdots & \rho^{T-1} \\ \rho & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \rho \\ \rho^{T-1} & \cdots & \rho & 1 \end{pmatrix}$$

- ► To implement FGLS:
  - The only parameter in Ω (besides σ<sub>ε</sub>, which cancels out in the expression for β<sub>FGLS</sub>), is ρ.
  - ▶ Denote the residual as ê the OLS residual from the original equation.
  - Now: perform the OLS regression of ĉ<sub>t</sub> on ĉ<sub>t-1</sub>. That the resulting ρ̂ is then consistent for ρ is true, but not trivial: to be entirely thorough this would need a short proof.
  - Define Ω(p̂) as the expression for Ω from previous slide, where p is replaced by its consistent estimator p̂.
  - Define  $\hat{\beta}_{FGLS} = (X'\Omega(\hat{\rho})^{-1}X)^{-1}X'\Omega(\hat{\rho})^{-1}Y$ .

Answer

- (d) ε<sub>t</sub> = ν<sub>t</sub> + λν<sub>t-1</sub>, with ν<sub>t</sub> i.i.d. with (conditional) expected value 0 and finite (conditional) variance σ<sup>2</sup><sub>ν</sub>. (The {ε<sub>t</sub>} sequence follows a MA(1) process).
- V(ε<sub>t</sub>) = σ<sub>ε</sub><sup>2</sup> = V(ν<sub>t</sub> + λν<sub>t-1</sub>) = σ<sub>ν</sub><sup>2</sup>(1 + λ<sup>2</sup>), i.e. σ<sub>ν</sub><sup>2</sup> = σ<sub>ε</sub><sup>σ<sub>ε</sub><sup>2</sup></sup>/(1+λ<sup>2</sup>). Likewise, this time we will have autocorrelation, but only first order. i.e., cov(ε<sub>t</sub>, ε<sub>t-1</sub>) = cov(ν<sub>t</sub> + λν<sub>t-1</sub>, ν<sub>t-1</sub> + λν<sub>t-2</sub>) = λσ<sub>ν</sub><sup>2</sup> = σ<sub>ε</sub><sup>2</sup> λ/(1+λ<sup>2</sup>); but, ∀s, t such that |t s| > 1, cov(ε<sub>t</sub>, ε<sub>s</sub>) = 0.

Hence in fine,

$$V(\epsilon) = c^2 \Omega = \sigma_\epsilon^2 \left( egin{array}{ccccc} 1 & rac{\lambda}{1+\lambda^2} & 0 & \cdots & 0 \ rac{\lambda}{1+\lambda^2} & 1 & \ddots & \ddots & 1 \ 0 & \ddots & \ddots & \ddots & 0 \ dots & \ddots & \ddots & \ddots & 0 \ dots & \ddots & \ddots & \ddots & 0 \ dots & \ddots & \ddots & \ddots & rac{\lambda}{1+\lambda^2} \ 0 & \cdots & 0 & rac{\lambda}{1+\lambda^2} & 1 \end{array} 
ight).$$

- ► To implement FGLS:
  - The only parameter in Ω (besides σ<sub>ν</sub>, which cancels out in the expression for β̂<sub>FGLS</sub>), is λ/(1+λ<sup>2</sup>).
  - ► We know that  $cov(\epsilon_t, \epsilon_{t-1}) = \frac{\lambda}{1+\lambda^2}\sigma\epsilon^2$ , which implies  $corr(\epsilon_t, \epsilon_{t-1}) = \frac{\lambda}{1+\lambda^2}$ .
  - This, intuitively, should lead us to consider the sample correlation between  $\hat{\epsilon_t}$  and  $\hat{\epsilon_{t-1}}$  and use it as an estimator for  $\frac{\lambda}{1+\lambda^2}$ . That the resulting estimator is then consistent for  $\frac{\lambda}{1+\lambda^2}$  is true, but not trivial: to be entirely thorough this would need a short proof.
  - Define  $\hat{\Omega}$  as the expression for  $\Omega$  from previous slide, where  $\frac{\lambda}{1+\lambda^2}$  is replaced by its consistent estimator.
  - Define  $\hat{\beta}_{FGLS} = (X'\hat{\Omega}^{-1}X)^{-1}X'\hat{\Omega}^{-1}Y.$

### Question

$$\triangleright \ y = X\beta + \epsilon, \ X: \ N \times 5.$$

• Want to test 
$$H_0$$
:  $\begin{array}{c} \beta_1\beta_2 = 1\\ \beta_3 = 4\beta_4 - 2 \end{array}$ 

### Answer

Problem: we are used to dealing with linear hypotheses. But this time, the first equation is non-linear in β.

• Rewrite 
$$H_0: g(\beta) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
 where  $g(\beta) = \begin{pmatrix} \beta_1 \beta_2 - 1 \\ \beta_3 - 4\beta_4 + 2 \end{pmatrix}$ .

### Theorem (Delta Method)

If  $x_n$  is a sequence of random variables such that  $\sqrt{n}(x_n - x) \rightarrow_d \mathcal{N}(0, \Sigma)$  and g is continuous and differentiable, then  $\sqrt{n}(g(x_n) - g(x)) \rightarrow_d \mathcal{N}(0, \frac{\partial g(x)}{\partial x'} \Sigma \frac{\partial g'(x)}{\partial x})$ .

- ▶ Here: we know (e.g. from PS7 question 1) that, under  $A1, A2, A3Rsru, \sqrt{N}(\hat{\beta}_{OLS} - \beta) \rightarrow_d \mathcal{N}(0, aVar(\hat{\beta}))$ . (Where aVar stands for "asymptotic variance".  $aVar(\hat{\beta}) = \sigma_{\varepsilon}^2 E(x_t x'_t)^{-1}$  under A4GM; and we have  $Var(\hat{\beta}) = \frac{aVar(\hat{\beta})}{N}$ ).
- ▶ Hence it is also the case that  $\sqrt{N}(g(\hat{\beta}) g(\beta)) \rightarrow_d \mathbb{N}(0, g_{\beta}(\hat{\beta}) a Var(\hat{\beta})g_{\beta}(\hat{\beta})')$ . Note that under  $H_0, g(\beta) = 0_2$ .
- ► This in turn implies that  $Ng(\hat{\beta})' \left(g_{\beta}(\hat{\beta})aVar(\hat{\beta})g_{\beta}(\hat{\beta})'\right)^{-1}g(\hat{\beta}) \rightarrow_{d} \chi^{2}(2).$  (Remember that if  $x \sim \mathcal{N}(0, \Sigma)$ , then  $x'\Sigma^{-1}x \sim \chi^{2}(rank(\Sigma))$
- Equivalently  $g(\hat{\beta})' \left( g_{\beta}(\hat{\beta}) Var(\hat{\beta}) g_{\beta}(\hat{\beta})' \right)^{-1} g(\hat{\beta}) \rightarrow_{d} \chi^{2}(2).$

- ► This asymptotic distribution will also hold (via Slutsky) if we replace  $Var(\hat{\beta})$  by a consistent estimator, e.g.  $\hat{Var}(\hat{\beta}) = s^2 (X'X)^{-1}$  if A4GM holds. We therefore recognize  $Q = g(\hat{\beta})' \left(g_{\beta}(\hat{\beta})\hat{V}(\hat{\beta})g_{\beta}(\hat{\beta})'\right)^{-1}g(\hat{\beta})$  as the Wald test statistic corresponding to hypothesis  $H_0$ .
- Hence, under  $H_0$ ,  $Q \rightarrow_d \chi^2(2)$ .

#### Answer

► Alternative approach: likelihood ratio test, based on the likelihood ratio:  $LR = \frac{L(\tilde{\beta})}{L(\hat{\beta})}$  where I define  $\hat{\beta}$  as the maximum likelihood estimator under the unconstrained model, and  $\tilde{\beta}$  as the maximum likelihood estimator under the (non-linear) constrained model. Then it can be shown that  $-2ln(LR) \rightarrow_d \chi^2(2)$ , and this test is asymptotically equivalent to the Wald test.

### Appendix

### Proof of consistency of $\theta$ in (a)

Let us consider the difference between θ̂, estimated using the ε̂ as outlined in the slides, and the (hypothetical) θ̂, estimated using the (unobserved) ε. Let us denote Z the 3 × 1 matrix of regressors containing an intercept, x<sub>3</sub><sup>2</sup> and 1/x<sub>ε</sub><sup>4</sup>.

Then:

$$\hat{\theta} - \tilde{\theta} = (Z'Z)^{-1}Z'(\hat{\varepsilon}^2) - (Z'Z)^{-1}Z'(\varepsilon^2) = (Z'Z)^{-1}Z'(\hat{\varepsilon}^2 - \varepsilon^2)$$

$$= (\frac{Z'Z}{T})^{-1}(\frac{\sum_t z'_t(\hat{\varepsilon}^2_t - \varepsilon^2_t)}{T})$$

$$= (\frac{Z'Z}{T})^{-1}(\frac{\sum_t z'_t(2\varepsilon_t x'_t(\beta - \hat{\beta}) + [x'_t(\beta - \hat{\beta})]^2}{T}) \quad (1)$$

## Appendix

### Proof of consistency of $\theta$ in (a)

In the last equation, I used the fact that:

$$\hat{\varepsilon_t} = y_t - x'_t \hat{\beta} = y_t - x'_t \beta + x'_t (\beta - \hat{\beta}) = \varepsilon_t + x'_t (\beta - \hat{\beta})$$

implying  $\hat{\varepsilon}_t^2 = \varepsilon_t^2 + [x_t'(\beta - \hat{\beta}]^2 + 2\varepsilon_t x_t'(\beta - \hat{\beta}).$ 

From (1), it is straightforward to see that the consistency of β for β implies that θ converges in probability to θ. Since the latter is consistent for θ, this means the former is also consistent, which is what we wanted to prove.