

Problem Set 1

1. Regression with $MA(1)$ errors

Consider a regression model with $MA(1)$ disturbance term

$$\begin{aligned} y_t &= x_t' \beta + u_t \\ u_t &= \varepsilon_t + \theta \varepsilon_{t-1}, \quad t = 1, \dots, T \end{aligned} \tag{1.1}$$

where $\varepsilon_t \sim iid(0, \sigma^2)$ with $\varepsilon_0 = 0$ and x_t non-stochastic.

1. Derive an expression for the covariance matrix, $\sigma^2 \Omega$, of the vector of disturbances $u = (u_1, \dots, u_T)'$ in terms of θ .

Answer. *Since*

$$\begin{aligned} E(u_t) &= 0, \text{var}(u_t) = E(u_t^2) = \sigma^2(1 + \theta^2) \quad t \geq 2 \\ E(u_t u_{t-1}) &= \theta \sigma^2, E(u_t u_{t-s}) = 0 \quad s > 1 \end{aligned}$$

we have that

$$\sigma^2 \Omega = \sigma^2 \begin{bmatrix} 1 & \theta & 0 & \dots & 0 \\ \theta & 1 + \theta^2 & \ddots & & \vdots \\ 0 & \theta & \ddots & \ddots & 0 \\ \vdots & \ddots & & \ddots & \theta \\ 0 & \dots & 0 & \theta & 1 + \theta^2 \end{bmatrix}$$

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2. By using $\varepsilon_t = u_t - \theta\varepsilon_{t-1}$ recursively, starting from $\varepsilon_0 = 0$, $\varepsilon_1 = u_1$, find the lower triangular matrix L such that $\varepsilon = Lu$ where $\varepsilon = (\varepsilon_1, \dots, \varepsilon_T)'$.

Answer. Since $\varepsilon_t = u_t - \theta\varepsilon_{t-1}$ and $\varepsilon_0 = 0$, we have that

$$\begin{aligned}\varepsilon_1 &= u_1 \\ \varepsilon_2 &= u_2 - \theta u_1 \\ \varepsilon_3 &= u_3 - \theta u_2 + \theta^2 u_1 \\ &\dots\end{aligned}$$

Hence

$$\begin{aligned}\varepsilon &= \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -\theta & 1 & 0 & \dots & 0 \\ \theta^2 & -\theta & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ (-\theta)^{T-1} & (-\theta)^{T-2} & \dots & -\theta & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ \vdots \\ \vdots \\ \vdots \\ u_T \end{bmatrix} \\ \varepsilon &= Lu.\end{aligned}$$

3. Assume θ is known. Noting that $\text{Var}(Lu) = \sigma^2 I$, determine a method for computing the best linear unbiased estimator of β which does not require the construction and inversion of Ω .

Answer. To estimate the model with known θ , rewrite (1.1) in matrix form and multiply through by L obtaining

$$\begin{aligned}Ly &= LX\beta + Lu \\ &= LX\beta + \varepsilon \quad \varepsilon \sim (0, \sigma^2 I).\end{aligned}$$

Hence OLS on this transformed model is BLUE.

2. $F - GLS$ estimation of the regression model with $AR(1)$ errors

Consider the model

$$\begin{aligned}y_t &= x_t' \beta + u_t \\ u_t &= \phi u_{t-1} + \varepsilon_t \quad t = 1, \dots, T\end{aligned} \tag{2.1}$$

where $|\phi| < 1$, $\varepsilon_t \sim iid(0, \sigma^2)$, x'_t and ε_t are process independent and

$$p \lim \frac{1}{T} \sum_{t=1}^T x_t x'_t = \Sigma_{xx}; \quad p \lim \frac{1}{T} \sum_{t=1}^T x_t x'_{t-1} = \Sigma_{xx-};$$

and Σ_{xx} is non-singular.

1. You estimate (2.1) by OLS and obtain the residual \hat{u}_t . You estimate ϕ by

$$\hat{\phi} = \frac{\sum_{t=2}^T \hat{u}_t \hat{u}_{t-1}}{\sum_{t=2}^T \hat{u}_{t-1}^2}.$$

Assuming that $\hat{\beta}_{OLS}$ is consistent, show that $\hat{\phi}$ is a consistent estimator of ϕ .

Answer. \hat{u}_t are the OLS residuals so:

$$\begin{aligned} \hat{u}_t &= y_t - \hat{y}_t \\ &= x'_t \beta + u_t - x'_t \hat{\beta} \\ &= -x'_t (\hat{\beta} - \beta) + u_t \end{aligned}$$

$$\begin{aligned} \therefore \frac{1}{T} \sum \hat{u}_t \hat{u}_{t-1} &= \frac{1}{T} \sum u_t u_{t-1} + (\hat{\beta} - \beta)' \frac{1}{T} \sum x_t x'_{t-1} (\hat{\beta} - \beta) \\ &\quad - (\hat{\beta} - \beta)' \frac{1}{T} \sum x_t u_{t-1} - (\hat{\beta} - \beta)' \frac{1}{T} \sum x_{t-1} u_t. \end{aligned}$$

Since: i) $\hat{\beta}$ is consistent so $p \lim (\hat{\beta} - \beta) = 0$, ii) $p \lim \frac{1}{T} \sum x_{t-1} u_t = 0$, $p \lim \frac{1}{T} \sum x_t u_{t-1} = 0$ (since x is process independent) and iii) $p \lim \frac{1}{T} \sum_{t=1}^T x_t x'_{t-1} = \Sigma_{xx-}$, we have that

$$p \lim \frac{1}{T} \sum \hat{u}_t \hat{u}_{t-1} = p \lim \frac{1}{T} \sum u_t u_{t-1}.$$

Similarly $p \lim \frac{1}{T} \sum \hat{u}_{t-1}^2 = p \lim \frac{1}{T} \sum u_{t-1}^2$. But u_t is an AR(1) hence $p \lim \frac{1}{T} \sum u_t^2 = \frac{\sigma^2}{(1-\phi^2)}$ and $p \lim \frac{1}{T} \sum u_t u_{t-1} = \frac{\phi \sigma^2}{(1-\phi^2)}$. Hence

$$\begin{aligned} p \lim \hat{\phi} &= \frac{p \lim \frac{1}{T} \sum \hat{u}_t \hat{u}_{t-1}}{p \lim \frac{1}{T} \sum \hat{u}_{t-1}^2} \\ &= \frac{\phi \sigma^2 / (1 - \phi^2)}{\sigma^2 / (1 - \phi^2)} = \phi. \end{aligned}$$

3. Maximum Likelihood of the ARMA(1,1)

Consider the $ARMA(1,1)$ process

$$y_t = \phi y_{t-1} + \varepsilon_t + \theta \varepsilon_{t-1} \quad t = 1, \dots, T$$

where $|\phi| < 1$, $\varepsilon_t \sim iidN(0, \sigma^2)$

1. Assuming, $y_1 = \varepsilon_1 = 0$ write down the log likelihood.
2. Obtain the FOCs wrt ϕ and θ .
3. Obtain

$$\frac{1}{T} I(\psi)$$

where $\psi := [\phi, \theta, \sigma^2]'$.

4. In finite sample we can approximate the distribution of $(\hat{\psi} - \psi_0)$ as a mean zero normal with covariance depending on $I(\hat{\psi})$. How would you estimate the covariance matrix?

Answer. *Since*

$$y_t | y_{t-1}, \varepsilon_{t-1} \sim N(\phi y_{t-1} + \theta \varepsilon_{t-1}, \sigma^2)$$

if we condition on $y_1, \varepsilon_1 = 0$

$$\begin{aligned} \text{Log} L(\phi, \theta, \sigma^2) &= -\frac{(T-1)}{2} \log 2\pi - \frac{(T-1)}{2} \log \sigma^2 \\ &\quad - \frac{1}{2\sigma^2} \sum_{t=2}^T (y_t - \phi y_{t-1} - \theta \varepsilon_{t-1})^2 \end{aligned}$$

This is nonlinear least squares where

$$\begin{aligned} \varepsilon_t &= y_t - \phi y_{t-1} - \theta \varepsilon_{t-1} \quad t = 2, \dots, T, \quad \varepsilon_1 = 0, \quad y_1 = 0 \\ z_t &= \begin{bmatrix} -\frac{\partial \varepsilon_t}{\partial \phi} \\ -\frac{\partial \varepsilon_t}{\partial \theta} \end{bmatrix} = \begin{bmatrix} y_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \phi} \\ \varepsilon_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \theta} \end{bmatrix}, \quad \frac{\partial \varepsilon_1}{\partial \phi} = \frac{\partial \varepsilon_1}{\partial \theta} = 0. \end{aligned}$$

Then

$$\begin{aligned} \begin{bmatrix} \frac{\partial \log L}{\partial \phi} \\ \frac{\partial \log L}{\partial \theta} \end{bmatrix} &= \begin{bmatrix} \frac{1}{\sigma^2} \sum \left(y_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \phi} \right) \varepsilon_t \\ \frac{1}{\sigma^2} \sum \left(\varepsilon_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \theta} \right) \varepsilon_t \end{bmatrix} = \frac{1}{\sigma^2} \sum_{t=2}^T z_t \varepsilon_t \\ \frac{\partial \log L}{\partial \sigma^2} &= -\frac{(T-1)}{2\sigma^2} + \frac{1}{2(\sigma^2)^2} \sum_{t=2}^T \varepsilon_t^2. \end{aligned}$$

Next, compute expected second derivatives, to compute $I(\psi)$. Recall

$$\begin{aligned} I(\psi) &= -E \begin{bmatrix} \frac{\partial^2 \log L}{\partial \phi^2} & \frac{\partial^2 \log L}{\partial \phi \partial \theta} & \frac{\partial^2 \log L}{\partial \phi \partial \sigma^2} \\ \frac{\partial^2 \log L}{\partial \theta \partial \phi} & \frac{\partial^2 \log L}{\partial \theta^2} & \frac{\partial^2 \log L}{\partial \theta \partial \sigma^2} \\ \frac{\partial^2 \log L}{\partial \sigma^2 \partial \phi} & \frac{\partial^2 \log L}{\partial \sigma^2 \partial \theta} & \frac{\partial^2 \log L}{\partial (\sigma^2)^2} \end{bmatrix} \\ -E \left(\frac{\partial^2 \log L}{\partial \phi^2} \right) &= \frac{1}{\sigma^2} \left(\sum E \left(y_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \phi} \right)^2 - \sum E \frac{\theta \partial^2 \varepsilon_{t-1}}{\partial \phi^2} \cdot \varepsilon_t \right). \end{aligned}$$

Since ε_t is iid, $E \frac{\theta \partial^2 \varepsilon_{t-1}}{\partial \phi^2} \varepsilon_t = \theta E \frac{\partial^2 \varepsilon_{t-1}}{\partial \phi^2} E(\varepsilon_t) = 0$. So

$$\begin{aligned} -E \left(\frac{\partial^2 \log L}{\partial \phi^2} \right) &= \frac{1}{\sigma^2} \sum E \left(y_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \phi} \right)^2 \\ -E \left(\frac{\partial^2 \log L}{\partial \theta \partial \phi} \right) &= \frac{1}{\sigma^2} \left(\sum E \left(y_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \phi} \right) \left(\varepsilon_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \theta} \right) \right. \\ &\quad \left. - \sum E \frac{\theta \partial^2 \varepsilon_{t-1}}{\partial \theta \partial \phi} \cdot \varepsilon_t - \sum E \frac{\partial \varepsilon_{t-1}}{\partial \phi} \varepsilon_t \right) \\ &= \frac{1}{\sigma^2} \left(\sum E \left(y_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \phi} \right) \left(\varepsilon_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \theta} \right) \right). \end{aligned}$$

The second and the third terms are zero by the same argument as above. Similarly

$$\begin{aligned} -E \left(\frac{\partial^2 \log L}{\partial \theta^2} \right) &= \frac{1}{\sigma^2} \sum E \left(\varepsilon_{t-1} + \frac{\theta \partial \varepsilon_{t-1}}{\partial \theta} \right)^2 \\ -E \left(\frac{\partial^2 \log L}{\partial \sigma^2 \partial \theta} \right) &= -E \left(\frac{\partial^2 \log L}{\partial \sigma^2 \partial \phi} \right) = 0 \\ -E \left(\frac{\partial^2 \log L}{\partial (\sigma^2)^2} \right) &= -E \left[\frac{(T-1)}{2(\sigma^2)^2} - \frac{1}{(\sigma^2)^3} \sum \varepsilon_t^2 \right] = \frac{(T-1)}{2(\sigma^2)^2} \end{aligned}$$

So

$$\begin{aligned} I(\psi) &= \begin{bmatrix} \frac{\sum E \left(y_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \phi} \right)^2}{\sigma^2} & \frac{\sum E \left(y_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \phi} \right) \left(\varepsilon_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \theta} \right)}{\sigma^2} & 0 \\ \frac{\sum E \left(\varepsilon_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \theta} \right) \left(y_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \phi} \right)}{\sigma^2} & \frac{\sum E \left(\varepsilon_{t-1} + \theta \frac{\partial \varepsilon_{t-1}}{\partial \theta} \right)^2}{\sigma^2} & 0 \\ 0 & 0 & \frac{(T-1)}{2(\sigma^2)^2} \end{bmatrix} \\ &= \frac{1}{\sigma^2} \begin{bmatrix} \sum E(z_t z_t') & 0 \\ 0 & \frac{(T-1)}{2\sigma^2} \end{bmatrix}. \end{aligned}$$

To approximate the variance-covariance matrix, replace θ , ϕ , σ^2 by $\hat{\theta}$, $\hat{\phi}$, $\hat{\sigma}^2$ and replace expectations by sample moments, i.e.

$$I(\hat{\psi})^{-1} \simeq \begin{bmatrix} \hat{\sigma}^2 (\sum z_t z'_t)^{-1} & 0 \\ 0 & \frac{2\hat{\sigma}^4}{(T-1)} \end{bmatrix}.$$