

Firm's maximization problem:

$$\max_{\{I_s\}_{s=t}^{\infty}, K_{s+1}} \sum_{s=t}^{\infty} (1+r)^{-(s-t)} \left[A_s \cdot F(K_s) - I_s - \pi \frac{I_s^2}{2} \right]$$

$$\text{s.t. } K_{s+1} = K_s + I_s, \quad \forall s, s=t, \dots, \infty$$

K_t given

$$J = \sum_{s=t}^{\infty} \frac{1}{(1+r)^{s-t}} \left\{ A_s \cdot F(K_s) - I_s - \pi \frac{I_s^2}{2} + \right. \\ \left. - q_s (K_{s+1} - K_s - I_s) \right\}$$

q_s is current value multiplier

$$a) \text{ FOC } I_s: (1+r)^{-(s-t)} \cdot [-1 - \pi I_s + q_s] = 0$$

$$\forall s, s=t, \dots, \infty$$

$$\text{FOC } K_s: (1+r)^{-(s-t)} [A_s F'(K_s) + q_s] = 0$$

$$\Leftrightarrow (1+r)^{-(s-1-t)} q_{s-1} = 0 \quad \forall s, s=t+1, \dots, \infty$$

$$\text{or } A_s F'(K_s) + q_s - (1+r) q_{s-1} = 0$$

b) For one unit of extra capital

$$q_1 = 1 + \pi I_1 \quad \text{--- unit of extra capital}$$

$$A_1 \bar{F}'(k_1) + q_1 - (1+\pi) q_{1-1} = 0$$

From the first one : $I_1 = \frac{q_1 - 1}{\pi}$

$$k_{1+1} - k_1 = \frac{q_1 - 1}{\pi}$$

From the second one : derive

$$A_{1+1} \bar{F}'(k_{1+1}) + q_{1+1} - q_1 - \pi q_1 = 0$$

$$q_{1+1} - q_1 = \pi q_1 - A_{1+1} \bar{F}'(k_{1+1})$$

$$q_{1+1} - q_1 = \pi q_1 - A_{1+1} \bar{F}'\left(k_1 + \frac{q_1 - 1}{\pi}\right)$$

c) Assume A constant. System of equations is

$$\begin{cases} k_{t+1} - k_t = \frac{q_t - 1}{\pi} \\ q_{t+1} - q_t = \pi q_t - A \cdot \bar{F}'\left(k_t + \frac{q_t - 1}{\pi}\right) \end{cases}$$

in k, q only

$$K_{t+1} = K_t \text{ for } q_t = 1$$

$$q_t > 1 \quad K_{t+1} > K_t$$

$$q_t < 1 \quad K_{t+1} < K_t$$

$$q_{t+1} = q_t \text{ for } q_t = \frac{\lambda}{\lambda} \cdot \frac{F'(K_t + \frac{q_t - 1}{\pi})}{\pi}$$

$q_t \uparrow \rightarrow$ LHS $\uparrow$ and $K_t + \frac{q_t - 1}{\pi} \uparrow$, so $F'(\cdot) \downarrow$, so

RHS $\downarrow \rightarrow$ need $K_t \downarrow$ so that RHS $\uparrow$

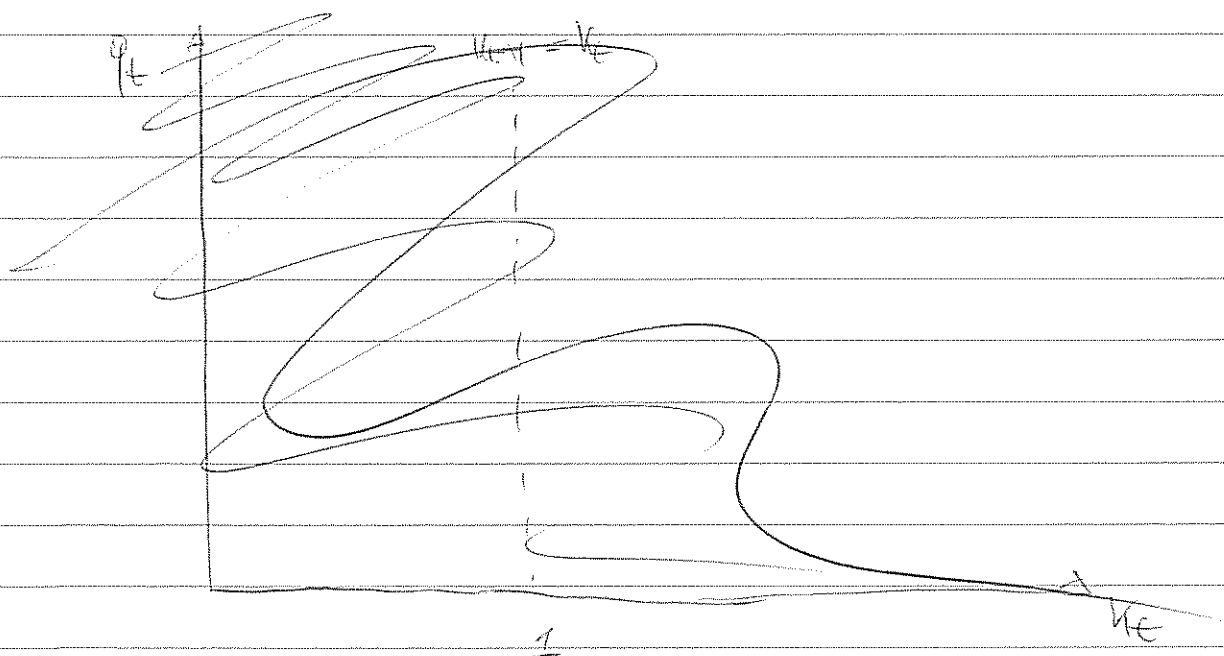
locus (q_t, K_t) is negatively sloped

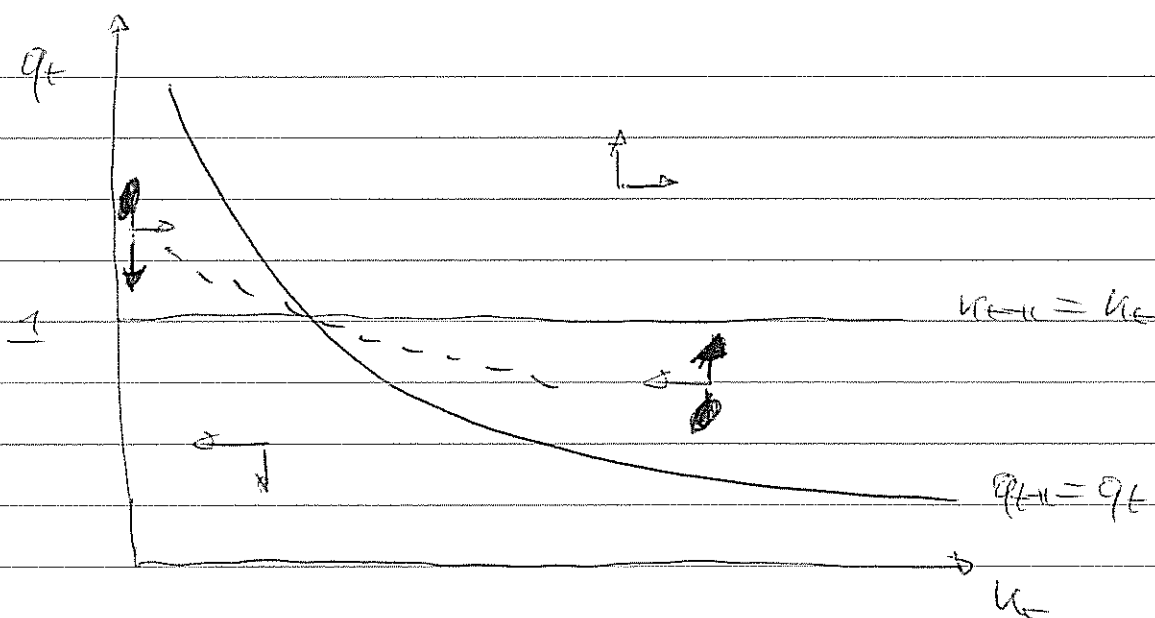
if K_t relatively too big (right of the line)

$\rightarrow q_t \uparrow$ (given q , $K \uparrow \rightarrow F' \downarrow \rightarrow$ RHS $\uparrow \Rightarrow q, \uparrow$)

if K_t relatively too small (left of the line)

$\rightarrow q_t \downarrow$





Note, in SS $q_t^{SS} = 1$, so

$$2 \cdot 1 = A \cdot F'(k_t + \frac{1-1}{\alpha})$$

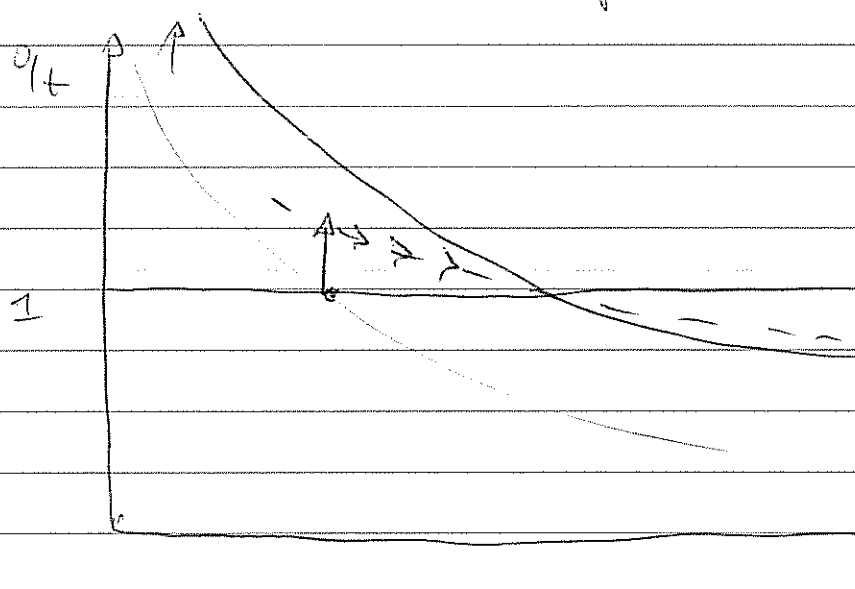
$$2 = A \cdot F'(k_{SS})$$

↳ constant, so 2
constant

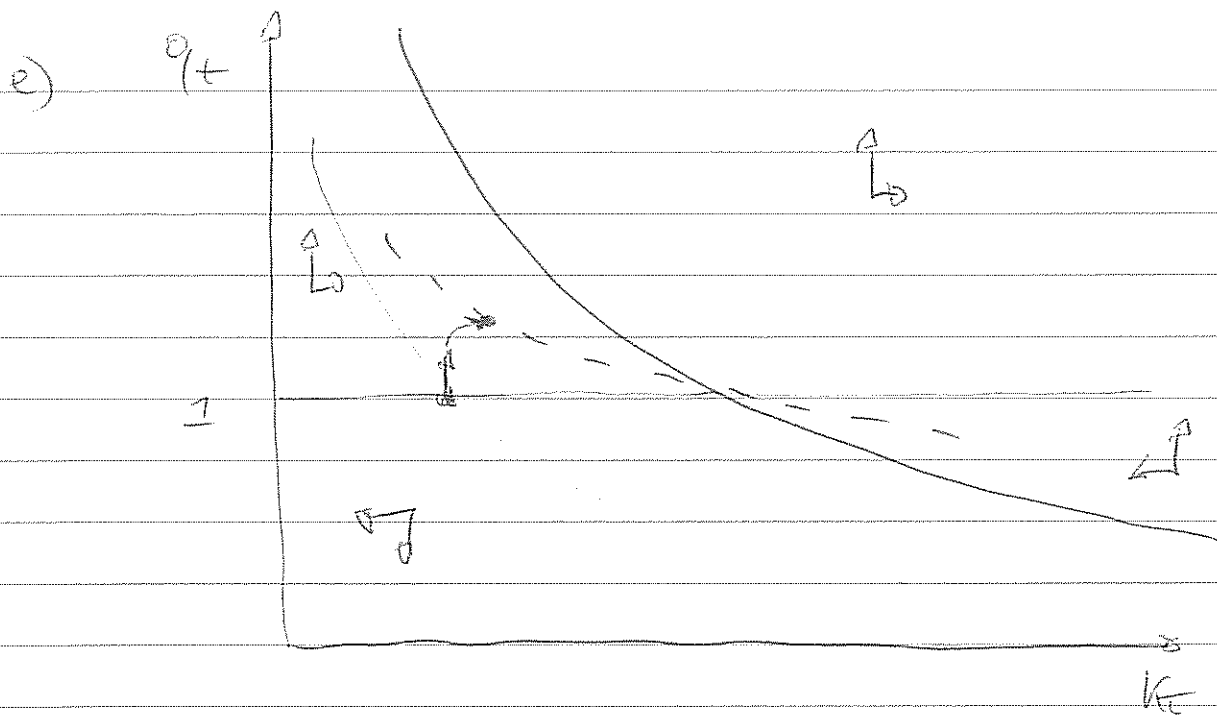
Standard optimality condition

a) $A \uparrow \rightarrow$ given q , need a k st. $F'(\cdot) \uparrow$, so

$k \uparrow \Rightarrow$ curve shift to the right



q_t jumps,
then follow
Saddle
path



f) No, since adjustment cost is
not linear homogeneous
(see O.R. p. 113)

